

# Differentiability of Torsion Theories

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## Abstract

We prove that every perfect torsion theory for a ring  $R$  is differential (in the sense of [2]). In this case, we construct the extension of a derivation of a right  $R$ -module  $M$  to a derivation of the module of quotients of  $M$ . Then, we prove that the Lambek and Goldie torsion theories for any  $R$  are differential.

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## 1 Introduction

The many important examples of rings in analysis and differential geometry have inspired an interest to study rings equipped with maps that have properties of a derivation. As the derivation on a ring is not intrinsically a ring theoretic notion, it is of interest to study how a derivation agrees with other ring theoretic notions. In [3] and [2], the authors study how derivations agree with an arbitrary hereditary torsion theory for that ring. Here, we continue this study by concentrating on some important classes and examples of hereditary torsion theories and prove that they are differential.

In Section 2, we recall the definition of derivation on a ring, a (hereditary) torsion theory, Gabriel filter and rings and modules of quotients. We also recall some important examples of torsion theories (Lambek, Goldie, classical, etc.).

In Section 3, we study perfect torsion theories. These are torsion theories in which the module of quotients of every module is (isomorphic to) the tensor product of the module with the right ring of quotients. Thus, a perfect torsion

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theory is a generalization of the classical torsion theory of a right Ore ring. As the classical torsion theory is differential, this leads us to suspect that a perfect torsion theory might be differential too. The main result of Section 3 states that this is indeed the case. Also, we give an explicit construction of the extension of derivation of a module to the derivation of the module of quotients of that module. We derive some corollaries of the main result.

In Section 4, we prove that the Lambek and Goldie torsion theories for every ring are differential.

## 2 Torsion Theories, Differential Filters, Modules of Quotients

Throughout this paper,  $R$  denotes an associative ring with a unit. By a module we mean a right module unless otherwise specified. We recall some definitions first.

A *derivation* on  $R$  is a mapping  $\delta : R \rightarrow R$  such that  $\delta(r+s) = \delta(r) + \delta(s)$  and  $\delta(rs) = \delta(r)s + r\delta(s)$  for all  $r, s \in R$ . A mapping  $d : M \rightarrow M$  on a right  $R$ -module  $M$  is a  $\delta$ -*derivation* if  $d(x+y) = d(x) + d(y)$  and  $d(xr) = d(x)r + x\delta(r)$  for all  $x \in M$  and  $r \in R$ . If  $M$  is a left  $R$ -module, the notion of  $\delta$ -derivation on  $M$  is defined analogously. The well known example of a derivation on a ring is obtained when considering  $\frac{d}{dx}$  on the polynomial ring  $R[x]$  over a ring  $R$ . An *inner derivation* is another example of a ring derivation. If  $R$  is a ring and  $a \in R$ , define the derivation  $\delta_a$  by  $\delta_a(b) = ab - ba$ . If  $M$  is an  $R$ -bimodule, then the map  $d_a$  on  $M$  given by  $d_a(m) = am - ma$  is a  $\delta_a$ -derivation on  $M$ . It is easy to see that the derivation  $\frac{d}{dx}$  on  $R[x]$  is not an inner derivation for some rings  $R$  (e.g. take  $R$  to be  $\mathbb{Q}$ ).

A *torsion theory* for  $R$  is a pair  $\tau = (\mathcal{T}, \mathcal{F})$  of classes of  $R$ -modules such that  $\mathcal{T}$  and  $\mathcal{F}$  are maximal classes having the property that  $\text{Hom}_R(T, F) = 0$ , for all  $T \in \mathcal{T}$  and  $F \in \mathcal{F}$ . The modules in  $\mathcal{T}$  are called *torsion modules* for  $\tau$  and the modules in  $\mathcal{F}$  are called *torsion-free modules* for  $\tau$ .

A given class  $\mathcal{T}$  is a torsion class of a torsion theory if and only if it is closed under quotients, direct sums and extensions. A class  $\mathcal{F}$  is a torsion-free class of a torsion theory if it is closed under taking submodules, isomorphic images, direct products and extensions (see Proposition 1.1.9 in [1]).

A torsion theory  $\tau = (\mathcal{T}, \mathcal{F})$  is *hereditary* if the class  $\mathcal{T}$  is closed under taking submodules (equivalently torsion-free class is closed under formation of injective envelopes, see Proposition 1.1.6, [1]). The largest torsion theory in which a given class of injective modules is torsion-free (the torsion theory *co-generated* by that class) is hereditary. Some authors (e.g. [4], [6]) consider just

hereditary torsion theories.

A torsion theory  $\tau = (\mathcal{T}, \mathcal{F})$  is *faithful* if  $R \in \mathcal{F}$ .

For every module  $M$ , the largest submodule of  $M$  that belongs to  $\mathcal{T}$  is called the *torsion submodule* of  $M$  and is denoted by  $\mathcal{T}M$  (see Proposition 1.1.4 in [1]). The quotient  $M/\mathcal{T}M$  is called the *torsion-free quotient* and is denoted by  $\mathcal{F}M$ .

If  $M$  is a right  $R$ -module with submodule  $N$  and  $m \in M$ , denote  $\{r \in R \mid mr \in N\}$  by  $(N : m)$ . Then  $(0 : m)$  is the annihilator  $\text{ann}(m)$ . A *Gabriel filter* (or *Gabriel topology*)  $\mathfrak{F}$  on a ring  $R$  is a nonempty collection of right ideals such that

- (1) If  $I \in \mathfrak{F}$  and  $r \in R$ , then  $(I : r) \in \mathfrak{F}$ .
- (2) If  $I \in \mathfrak{F}$  and  $J$  is a right ideal with  $(J : r) \in \mathfrak{F}$  for all  $r \in I$ , then  $J \in \mathfrak{F}$ .

If  $\tau = (\mathcal{T}, \mathcal{F})$  is a hereditary torsion theory, the collection of right ideals  $\{I \mid R/I \in \mathcal{T}\}$  is a Gabriel filter. Conversely, if  $\mathfrak{F}$  is a Gabriel filter, then the class of modules  $\{M \mid \text{ann}(m) \in \mathfrak{F} \text{ for every } m \in M\}$  is a torsion class of a hereditary torsion theory. The details can be found in [1] or [8].

We recall some important examples of torsion theories.

**Example 1** (1) The torsion theory cogenerated by the injective envelope  $E(R)$  of  $R$  is called the *Lambek torsion theory*. It is hereditary, as it is cogenerated by an injective module, and faithful. Moreover, it is the largest hereditary faithful torsion theory. The Gabriel filter of this torsion theory is the set of all dense right ideals (see Proposition VI 5.5, p. 147 in [8]).

(2) The class of nonsingular modules over a ring  $R$  is closed under submodules, extensions, products and injective envelopes. Thus, it is a torsion-free class of a hereditary torsion theory. This torsion theory is called the *Goldie torsion theory*. It is larger than any hereditary faithful torsion theory (see Example 3, p. 26 in [1]). So, the Lambek torsion theory is smaller than the Goldie's. If  $R$  is right nonsingular, the Lambek and Goldie torsion theories coincide (see p. 26 in [1] or p. 149 in [8]).

(3) If  $R$  is a right Ore ring with the set of regular elements  $T$  (i.e.,  $rT \cap tR \neq 0$ , for every  $t \in T$  and  $r \in R$ ), we can define a hereditary torsion theory by the condition that a right  $R$ -module  $M$  is a torsion module iff for every  $m \in M$ , there is a nonzero  $t \in T$  such that  $mt = 0$ . This torsion theory is called the *classical torsion theory of a right Ore ring*. It is hereditary and faithful.

(4) Let  $R$  be a subring of a ring  $S$ . The collection of all  $R$ -modules  $M$  such that  $M \otimes_R S = 0$  is closed under quotients, extensions and direct sums. Moreover,

if  $S$  is flat as a left  $R$ -module, then this collection is closed under submodules and, hence, defines a hereditary torsion theory. We denote this torsion theory by  $\tau_S$ . As all flat modules are  $\tau_S$ -torsion-free,  $\tau_S$  is faithful. If  $R$  is a right Ore ring, then  $\tau_{Q_{\text{cl}}^r(R)}$  is the classical torsion theory.

A Gabriel filter  $\mathfrak{F}$  is a *differential filter* if for every  $I \in \mathfrak{F}$  there is  $J \in \mathfrak{F}$  such that  $\delta(J) \subseteq I$  for all derivations  $\delta$ . The hereditary torsion theory determined by  $\mathfrak{F}$  is said to be a *differential torsion theory* in this case. By Lemma 1.5 from [2], a torsion theory is differential if and only if

$$d(\mathcal{T}M) \subseteq \mathcal{T}M$$

for every right  $R$ -module  $M$ , every derivation  $\delta$  and every  $\delta$ -derivation  $d$  on  $M$ .

Examples 1.1 – 1.4, page 3, from [2] provide some examples of differential torsion theories:

- (1) If  $R$  is commutative, every Gabriel filter  $\mathfrak{F}$  is differential as  $\delta(I^2) \subseteq I$  for all  $I \in \mathfrak{F}$ .
- (2) If the torsion class  $\mathcal{T}$  is closed for products, then it is differential (for details see Example 1.2, page 3 in [2]). As a consequence, every hereditary torsion theory for a left perfect ring is differential.
- (3) By Example 1.4, page 3, from [2], the classical torsion theory of a right Ore ring is differential.

If  $\tau$  is a hereditary torsion theory with Gabriel filter  $\mathfrak{F}$  and  $M$  is a right  $R$ -module, define the module  $M_{\mathfrak{F}}$  as the largest submodule  $N$  of  $E(M/\mathcal{T}M)$  such that  $N/(M/\mathcal{T}M)$  is torsion module (i.e. the closure of  $M/\mathcal{T}M$  in  $E(M/\mathcal{T}M)$ ). In [6] (definition of  $Q(M)$  on page 11 and Example 5 on page 25) and [8] (exposition on pages 195–197) it is shown that  $R_{\mathfrak{F}}$  has a ring structure and that  $M_{\mathfrak{F}}$  has a structure of a right  $R_{\mathfrak{F}}$ -module. The ring  $R_{\mathfrak{F}}$  is called the *right ring of quotients with respect to the torsion theory  $\tau$*  and  $M_{\mathfrak{F}}$  is called the *module of quotients* of  $M$  with respect to  $\tau$ .

For example,  $Q_{\text{max}}^r(R)$  is the right ring of quotients with respect to the Lambek torsion theory (Example 1, page 200, [8]).  $E(\mathcal{F}R)$  is the right ring of quotients with respect to the Goldie torsion theory if  $\mathcal{F}R$  is the torsion free quotient of  $R$  in the Goldie torsion theory (Propositions IX 1.7, 2.5, 2.7, and 2.11 and Lemma IX 2.10 in [8]).  $Q_{\text{cl}}^r(R)$  is the right ring of quotients with respect to classical torsion theory if  $R$  is right Ore (Example 2, page 200, [8]).

Consider the map  $\phi_M : M \rightarrow M_{\mathfrak{F}}$  obtained by composing the projection  $M \rightarrow M/\mathcal{T}M$  with the injection  $M/\mathcal{T}M \rightarrow M_{\mathfrak{F}}$ . Then, the kernel and cokernel of  $\phi_M$  are torsion modules and  $M_{\mathfrak{F}}$  is torsion-free (Lemmas 1.2 and 1.5, page 196, in [8]). In Corollary 1 of [3], Golan has shown that for the differential

filter  $\mathfrak{F}$  and the  $\delta$ -derivation  $d_M$  of a right  $R$ -module  $M$ ,  $d_M$  extends to a derivation  $d_{M_{\mathfrak{F}}}$  of the module of quotients  $M_{\mathfrak{F}}$  such that  $d_{M_{\mathfrak{F}}}\phi_M = \phi_M d_M$ . Bland proved that such extension is unique and that the converse is also true. Namely, Proposition 2.3 of his paper [2] states the following.

**Theorem 2** *Let  $\mathfrak{F}$  be a Gabriel filter. The filter  $\mathfrak{F}$  is differential if and only if every derivation on any module  $M$  extends uniquely to a derivation on the module of quotients  $M_{\mathfrak{F}}$ .*

### 3 Differentiability of a Perfect Torsion Theory

A ring homomorphism  $f : R \rightarrow S$  is a *ring epimorphism* if for all rings  $T$  and homomorphisms  $g, h : S \rightarrow T$ ,  $gf = hf$  implies  $g = h$ . The situation when  $S$  is flat as left  $R$ -module is of special interest. If  $f : R \rightarrow S$  is a ring epimorphism with  $S$  flat as left  $R$ -module, then  $S$  is a right ring of quotients with respect to the torsion theory with Gabriel filter  $\mathfrak{F} = \{I \mid f(I)S = S\}$ .  $S$  is called a *perfect right ring of quotients*, a *flat epimorphic extension* of  $R$ , or a *perfect right localization* of  $R$  in this case. A hereditary torsion theory  $\tau$  with Gabriel filter  $\mathfrak{F}$  is called *perfect* if the right ring of quotients  $R_{\mathfrak{F}}$  is perfect and  $\mathfrak{F} = \{I \mid \phi_I(I)R_{\mathfrak{F}} = R_{\mathfrak{F}}\}$ . The Gabriel filter  $\mathfrak{F}$  is called *perfect* in this case.

Perfect filters have a nice description. For a Gabriel filter  $\mathfrak{F}$ , let us look at the canonical maps  $i_M : M \rightarrow M \otimes_R R_{\mathfrak{F}}$  and  $\phi_M : M \rightarrow M_{\mathfrak{F}}$ . There is a unique  $R_{\mathfrak{F}}$ -map  $\Phi_M : M \otimes_R R_{\mathfrak{F}} \rightarrow M_{\mathfrak{F}}$  such that  $\phi_M = \Phi_M i_M$ . The perfect filters are characterized by the property that the map  $\Phi_M$  is an isomorphism for every module  $M$ . More details can be found in [8] (Theorem XI 3.4, p. 231). Also, a perfect filter coincides with the filter of torsion theory  $\tau_{R_{\mathfrak{F}}}$  obtained by tensoring with the ring of quotients  $R_{\mathfrak{F}}$  (for details see Lemma 8 in [11]).

We show that all perfect filters are differential. First we need an easy lemma.

**Lemma 3** *If  $M$  is a right  $R$ -module,  $N$  is an  $R$ -bimodule,  $d_M$  and  $d_N$   $\delta$ -derivations and  $1_M$  and  $1_N$  identity mappings on  $M$  and  $N$ , then the map  $d = d_{M \otimes_R N} : M \otimes_R N \rightarrow M \otimes_R N$  defined by  $d = d_M \otimes 1_N + 1_M \otimes d_N$  is a  $\delta$ -derivation.*

**PROOF.** Clearly the map  $d$  is additive. Let  $m \in M, n \in N$  and  $r \in R$  be arbitrary.  $d((m \otimes n)r) = d(m \otimes nr) = d_M(m) \otimes nr + m \otimes d_N(nr) = d_M(m) \otimes nr + m \otimes d_N(n)r + m \otimes n\delta(r) = (d(m \otimes n))r + (m \otimes n)\delta(r)$ . From this observation and the additivity of  $d$  it follows that  $d$  is a  $\delta$ -derivation.  $\square$

Now we show the main result of this section.

**Proposition 4** *If a Gabriel filter  $\mathfrak{F}$  is perfect, then it is differential.*

**PROOF.** By Theorem 2, it is sufficient to show that the derivation  $d_M : M \rightarrow M$  extends uniquely to a derivation  $d_{M_{\mathfrak{F}}} : M_{\mathfrak{F}} \rightarrow M_{\mathfrak{F}}$  such that  $d_{M_{\mathfrak{F}}}\phi_M = \phi_M d_M$ , for every module  $M$ . This is automatically fulfilled if  $M$  is torsion-free by Corollary 2.2 in [2]. If  $\mathfrak{F}$  is perfect,  $R$  is torsion-free (as the torsion submodule of  $R$  with respect to a perfect torsion theory is isomorphic to  $\text{Tor}_1^R(R, R_{\mathfrak{F}}/R) = 0$ , see Theorem XI 3.4, p. 231 in [8]) so we obtain the unique extension  $\delta_{R_{\mathfrak{F}}}$  of  $\delta$  to a derivation of  $R_{\mathfrak{F}}$ .

As  $\mathfrak{F}$  is perfect, the unique map  $\Phi_M : M \otimes_R R_{\mathfrak{F}} \rightarrow M_{\mathfrak{F}}$  such that  $\phi_M = \Phi_M i_M$  is an isomorphism for every module  $M$ . Define

$$d_{M_{\mathfrak{F}}} = \Phi_M d_{M \otimes_R R_{\mathfrak{F}}} \Phi_M^{-1}$$

where map  $d_{M \otimes_R R_{\mathfrak{F}}}$  is map from Lemma 3 defined via  $d_M$  and  $\delta_{R_{\mathfrak{F}}}$ .

Clearly,  $d_{M_{\mathfrak{F}}}$  is additive and a short, straightforward calculation shows that it is a derivation. We show that the following diagram commutes

$$\begin{array}{ccccc} M & \xrightarrow{i_M} & M \otimes_R R_{\mathfrak{F}} & \xrightarrow{\Phi_M} & M_{\mathfrak{F}} \\ \downarrow d_M & & \downarrow d_{M \otimes_R R_{\mathfrak{F}}} & & \downarrow d_{M_{\mathfrak{F}}} \\ M & \xrightarrow{i_M} & M \otimes_R R_{\mathfrak{F}} & \xrightarrow{\Phi_M} & M_{\mathfrak{F}} \end{array}$$

As  $\delta(1) = 0$ ,  $\delta_{R_{\mathfrak{F}}}(1) = 0$ . Thus, if  $m \in M$  is arbitrary,  $d_{M \otimes_R R_{\mathfrak{F}}} i_M(m) = d_{M \otimes_R R_{\mathfrak{F}}}(m \otimes 1) = d_M(m) \otimes 1 + 0 = i_M(d_M(m))$ . So,  $d_{M \otimes_R R_{\mathfrak{F}}} i_M = i_M d_M$ .  $d_{M_{\mathfrak{F}}}\Phi_M = \Phi_M d_{M \otimes_R R_{\mathfrak{F}}}$  by definition of  $d_{M_{\mathfrak{F}}}$ . This gives us

$$\begin{aligned} d_{M_{\mathfrak{F}}}\phi_M &= \Phi_M d_{M \otimes_R R_{\mathfrak{F}}} \Phi_M^{-1} \phi_M \quad (\text{definition of } d_{M_{\mathfrak{F}}}) \\ &= \Phi_M d_{M \otimes_R R_{\mathfrak{F}}} i_M \quad (\text{as } \phi_M = \Phi_M i_M) \\ &= \Phi_M i_M d_M \quad (\text{by the above diagram}) \\ &= \phi_M d_M \quad (\text{as } \phi_M = \Phi_M i_M). \end{aligned}$$

Finally,  $d_{M_{\mathfrak{F}}}$  is unique by Proposition 2.1 in [2].  $\square$

**Remark 5** It is possible to give the explicit description of the derivation  $\delta_{R_{\mathfrak{F}}}$  extending  $\delta$  on the right ring of quotients  $R_{\mathfrak{F}}$  if  $\mathfrak{F}$  is perfect. Namely, if  $\mathfrak{F}$  is perfect, then every element  $q \in R_{\mathfrak{F}}$  has the property

$$qr_j \in R \text{ and } \sum_{j=1}^n r_j q_j = 1 \text{ for some } n, q_j \in R_{\mathfrak{F}} \text{ and } r_j \in R, j = 1, \dots, n.$$

For proof see Theorem 2.1, p. 227 of [8]. By the above property,  $q = q1 = \sum qr_j q_j$ . To define  $\delta_{R_{\mathfrak{F}}}$  to be a derivation extending  $\delta$  we need  $\delta_{R_{\mathfrak{F}}}(q) = \sum(\delta(qr_j)q_j + qr_j\delta_{R_{\mathfrak{F}}}(q_j))$ . To define this, it is sufficient to define the sum  $\sum r_j\delta_{R_{\mathfrak{F}}}(q_j)$ . As  $\sum r_j q_j = 1$ , we can define  $\sum r_j\delta_{R_{\mathfrak{F}}}(q_j)$  to be  $\delta(1) - \sum \delta(r_j)q_j = -\sum \delta(r_j)q_j$ . Thus define

$$\delta_{R_{\mathfrak{F}}}(q) = \sum_{j=1}^n (\delta(qr_j)q_j - q\delta(r_j)q_j)$$

**Corollary 6** *If  $\mathfrak{F}$  is a perfect filter,  $M$  a right  $R$ -module and  $d_M$  derivation on  $M$ , then the unique derivation extending  $d_M$  to the module of quotients  $M_{\mathfrak{F}}$  is given by*

$$d_{M_{\mathfrak{F}}}(x) = \Phi_M \left( \sum_i d_M(m_i) \otimes q_i + m_i \otimes \sum_j (\delta(q_i r_{ij})q_{ij} - q_i \delta(r_{ij})q_{ij}) \right)$$

where  $\Phi_M(\sum_i m_i \otimes q_i) = x$ ,  $m_i \in M$  and  $q_i \in R_{\mathfrak{F}}$  and  $r_{ij} \in R$ ,  $q_{ij} \in R_{\mathfrak{F}}$  are such that  $q_i r_{ij} \in R$  for all  $i$  and  $j$  and  $\sum_j r_{ij} q_{ij} = 1$  for all  $i$ .

**PROOF.** The proof follows directly from the remark above and the proof of Proposition 4.  $\square$

The converse of the Proposition 4 is not true. Any infinite group  $G$  gives rise to the group von Neumann algebra  $\mathcal{N}G$  that is not semisimple (see Exercise 9.11, p. 367 in [7]) and so the Lambek torsion theory of  $\mathcal{N}G$  is not perfect (by Theorem 23 (3) in [10], Theorem 12 from [11] and Theorem 4 in [9]). However, if  $G$  is abelian and infinite, every torsion theory for  $\mathcal{N}G$  is differential as  $\mathcal{N}G$  is abelian. Another example of a ring with the Lambek torsion theory that is differential but not perfect is the ring from Example 4.2 in [11].

The following is a direct corollary of Proposition 4.

**Corollary 7** *If  $R$  is right noetherian and hereditary, then all hereditary torsion theories are differential. In particular, a semisimple ring has all hereditary torsion theories differential.*

**PROOF.** If  $R$  is right noetherian and hereditary, then all torsion theories are perfect (Corollary 3.6, p. 232 in [8]).  $\square$

**Corollary 8** *If  $R$  is right semihereditary and  $S$  is an extension of  $R$  that is flat as left  $R$ -module, then  $\tau_S$  is differential.*

**PROOF.** We show that the assumptions of the claim imply that  $\tau_S$  is perfect. Then the claim follows from Proposition 4.

By the definition of  $\tau_S$ , its filter  $\mathfrak{F}$  consists of the right ideals  $I$  such that  $IS = S$ . This filter has a base of finitely generated ideals as if  $I \in \mathfrak{F}$ , then  $1 \in S = IS$  so there is a nonnegative integer  $n$ ,  $r_i \in I$  and  $s_i \in S$ ,  $i = 1, \dots, n$  such that  $\sum r_i s_i = 1$ . Thus the ideal  $J = \langle r_1, \dots, r_n \rangle$  is finitely generated ideal in  $\mathfrak{F}$  with  $J \subseteq I$ .

As  $R$  is right semihereditary, every finitely generated right ideal is projective. Thus,  $\mathfrak{F}$  has a base of projective ideals. But then  $\tau_S$  is perfect by Proposition 3.3, p. 230 and Proposition 3.4, p. 231 in [8].  $\square$

#### 4 Differentiability of the Lambek and Goldie Torsion Theories

First, we show that the Lambek torsion theory is differential. Recall that for a right module  $M$  and  $x \in M$ ,  $x$  is in the torsion submodule with respect to Lambek torsion theory if and only if  $\text{ann}(x)$  is a dense right ideal. Recall also that a right ideal  $I$  is dense if and only if for every  $r, s \in R$  such that  $s \neq 0$ , there is  $t \in R$  such that  $st \neq 0$  and  $rt \in I$ .

**Proposition 9** *The Lambek torsion theory for any ring  $R$  is differential.*

**PROOF.** Let  $M$  be any  $R$ -module and  $x$  any element of  $M$ . For the Lambek torsion theory to be differential it is sufficient to show that  $\text{ann}(d(x))$  is dense, whenever  $\text{ann}(x)$  is a dense right ideal.

Let  $\text{ann}(x)$  be dense and let  $r, s \in R$ ,  $s \neq 0$ . As  $\text{ann}(x)$  is dense, there is  $t_1 \in R$  such that  $st_1 \neq 0$  and  $xrt_1 = 0$ . As  $\text{ann}(x)$  is dense, for  $\delta(rt_1)$  and  $st_1 \neq 0$  there is  $t_2 \in R$  such that  $st_1 t_2 \neq 0$  and  $x\delta(rt_1)t_2 = 0$ .

$xrt_1 = 0$  implies that  $d(xrt_1) = 0$ . Thus  $d(x)rt_1 = -x\delta(rt_1)$ . So,  $d(x)rt_1 t_2 = -x\delta(rt_1)t_2 = 0$ . Thus, for  $r$  and  $s \neq 0$ , we have found  $t = t_1 t_2$  such that  $rt \in \text{ann}(d(x))$  and  $st \neq 0$ . Hence,  $\text{ann}(d(x))$  is dense.  $\square$

If  $R$  is right nonsingular, the Goldie and Lambek torsion theories coincide. Thus, from Proposition 9 it follows that the Goldie torsion theory of a right nonsingular ring is differential. We show that this is the case even if  $R$  is not right nonsingular. Let  $\mathfrak{F}_G$  denotes the Gabriel filter of the Goldie torsion theory. Then all the essential ideals are in  $\mathfrak{F}_G$  and

$$\mathfrak{F}_G = \{I \mid \text{there exists } J, I \subseteq J, J \subseteq_e R \text{ and } (I : j) \subseteq_e R \text{ for all } j \in J\}.$$

For proof see Proposition 6.3, p. 148 in [8]. From this observation it is easy to see that

$$\mathfrak{F}_G = \{I \mid \{r \in R \mid (I : r) \subseteq_e R\} \subseteq_e R\}.$$

Thus, if  $M$  is a right  $R$ -module and  $x$  is an element of  $M$ ,  $x$  is in the torsion submodule for Goldie torsion theory (i.e.  $\text{ann}(x) \in \mathfrak{F}_G$ ) if and only if

$$\{r \in R \mid \text{ann}(xr) \subseteq_e R\} \subseteq_e R.$$

We shall follow the notation from [5] (see p. 255 of [5]) and denote

$$\begin{aligned} \text{ann}(x)^* &= \{r \in R \mid \text{ann}(xr) \subseteq_e R\} \text{ and} \\ \text{ann}(x)^{**} &= \{r \in R \mid \{s \mid \text{ann}(xrs) \subseteq_e R\} \subseteq_e R\}. \end{aligned}$$

Using this notation,  $\text{ann}(x) \in \mathfrak{F}_G$  if and only if  $\text{ann}(x)^* \subseteq_e R$ .

To prove the main result, we need four lemmas.

**Lemma 10** *If  $M$  is a right  $R$ -module and  $x \in M$ , then the following are equivalent*

- (1)  $\text{ann}(x) \in \mathfrak{F}_G$ ,
- (2)  $\text{ann}(x)^* \subseteq_e R$ ,
- (3)  $\text{ann}(x)^{**} \subseteq_e R$ .

**PROOF.** (1) and (2) are equivalent by the observation above. (2) implies (3) as  $\text{ann}(x)^* \subseteq_e \text{ann}(x)^{**}$  (for details see p.255 in [5]). (3) implies (2) by the transitivity of relation  $\subseteq_e$  and because  $\text{ann}(x)^* \subseteq_e \text{ann}(x)^{**}$  (Proposition 7.29 (2), p. 255 in [5]).  $\square$

**Lemma 11** *Let  $M$  be a right  $R$ -module and  $x, y \in M$ . Then*

- (1)  $\text{ann}(x) \subseteq_e R$  implies  $\text{ann}(xr) \subseteq_e R$  for any  $r \in R$ .
- (2)  $\text{ann}(x)^* \subseteq_e R$  implies  $\text{ann}(xr)^* \subseteq_e R$  for any  $r \in R$ .
- (3)  $\text{ann}(x)^* \subseteq_e R$  and  $\text{ann}(y)^* \subseteq_e R$  imply  $\text{ann}(x+y)^* \subseteq_e R$ .

**PROOF.** (1) follows from Lemma 7.2, p. 246 in [5]. (2) and (3) are true as  $x, y \in \mathcal{T}M$  implies that  $xr \in \mathcal{T}M$  and  $x+y \in \mathcal{T}M$  where  $\mathcal{T}M$  is the torsion submodule of  $M$  for the Goldie torsion theory.  $\square$

**Lemma 12** *If  $M$  is a right  $R$ -module and  $x \in M$  is such that  $\text{ann}(x) \subseteq_e R$ , then  $\text{ann}(d(x))^* \subseteq_e R$ .*

**PROOF.** Let  $r \in R$ . As  $\text{ann}(x) \subseteq_e R$ , there is  $s \in R$ ,  $rs \neq 0$  and  $xrs = 0$ . Thus  $0 = d(xrs) = d(x)rs + x\delta(rs)$ . As  $\text{ann}(x)$  is essential,  $\text{ann}(x\delta(rs))$  is also essential by part (1) of Lemma 11. Thus,  $\text{ann}(d(x)rs) = \text{ann}(-x\delta(rs))$  is essential as well and  $0 \neq rs \in \text{ann}(d(x))^*$ . So  $\text{ann}(d(x))^*$  is essential.  $\square$

**Lemma 13** *If  $M$  is a right  $R$ -module and  $x \in M$  is such that  $\text{ann}(x)^* \subseteq_e R$ , then  $\text{ann}(d(x))^{**} \subseteq_e R$ .*

**PROOF.** Let  $r$  be arbitrary element of  $R$ . As  $\text{ann}(x)^* \subseteq_e R$ , there is  $s \in R$ ,  $rs \neq 0$  and  $\text{ann}(xrs) \subseteq_e R$ . By Lemma 12,  $\text{ann}(d(xrs))^* \subseteq_e R$ . By part (2) of Lemma 11,  $\text{ann}(x)^* \subseteq_e R$  implies that  $\text{ann}(x\delta(rs))^* \subseteq_e R$ . But then  $\text{ann}(d(x)rs)^* = \text{ann}(d(xrs) - x\delta(rs))^*$  is essential in  $R$  by part (3) of Lemma 11. Thus,  $\{t \mid \text{ann}(d(x)rst) \subseteq_e R\} \subseteq_e R$  and so  $0 \neq rs \in \text{ann}(d(x))^{**}$ .  $\square$

**Proposition 14** *The Goldie torsion theory for any ring  $R$  is differential.*

**PROOF.** Let  $M$  be a right  $R$ -module and  $x \in M$  such that  $\text{ann}(x) \in \mathfrak{F}_G$ . Then  $\text{ann}(x)^* \subseteq_e R$  by Lemma 10 and so  $\text{ann}(d(x))^{**} \subseteq_e R$  by Lemma 13. But this implies that  $\text{ann}(d(x)) \in \mathfrak{F}_G$  by Lemma 10.  $\square$

Theorem 2, Proposition 4, Proposition 9, and Proposition 14 yield the following corollary.

**Corollary 15** *If a Gabriel filter  $\mathfrak{F}$  is perfect, Lambek or Goldie, then every derivation on any module  $M$  lifts uniquely to a derivation on the module of quotients  $M_{\mathfrak{F}}$ . In particular, every derivation on  $R$  uniquely lifts to a derivation of  $R_{\mathfrak{F}}$ .*

In this paper, we have shown that some important examples of hereditary torsion theories are differential. This leads us to raise the question whether every hereditary torsion theory is differential.

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